

# Iterative Instance Segmentation

## Supplementary Material

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### 1. Per-Category Performance Comparison

We report the per-category performance of the proposed method compared to the state-of-the-art below.

Method and Setting	aero	bike	bird	boat	bottle	bus	car	cat	chair	cow	
<i>Raw pixel-wise prediction:</i>											
Hypercolumn [16]	74.8	57.4	61.6	38.3	32.3	79.1	57.9	82.3	20.8	55.2	
Proposed Method	<b>77.3</b>	<b>65.3</b>	<b>65.5</b>	<b>42.5</b>	<b>35.4</b>	<b>80.3</b>	<b>62.2</b>	<b>83.9</b>	<b>27.2</b>	<b>61.6</b>	
<i>With superpixel projection:</i>											
Hypercolumn [16]	<b>76.4</b>	63.4	63.8	<b>42.9</b>	32.3	80.0	59.5	<b>82.4</b>	27.5	59.9	
Proposed Method	76.3	<b>64.9</b>	<b>65.1</b>	42.6	<b>35.1</b>	<b>80.6</b>	<b>61.2</b>	80.9	<b>28.3</b>	<b>61.7</b>	
<i>With superpixel projection and rescoring:</i>											
Hypercolumn [16]	78.2	67.0	68.2	46.9	42.0	<b>82.9</b>	66.7	<b>85.0</b>	<b>31.2</b>	<b>66.7</b>	
Proposed Method	<b>79.2</b>	<b>67.9</b>	<b>70.0</b>	<b>47.9</b>	<b>45.3</b>	81.6	<b>68.8</b>	84.1	30.4	65.5	
Method and Setting	table	dog	horse	mbike	person	plant	sheep	sofa	train	tv	mAP <sup>r</sup>
<i>Raw pixel-wise prediction:</i>											
Hypercolumn [16]	27.5	80.0	65.3	69.6	52.4	27.5	58.1	44.7	77.5	59.9	56.1
Proposed Method	<b>32.4</b>	<b>82.3</b>	<b>70.9</b>	<b>71.4</b>	<b>63.1</b>	<b>31.3</b>	<b>63.6</b>	<b>44.9</b>	<b>78.3</b>	<b>62.4</b>	<b>60.1</b>
<i>With superpixel projection:</i>											
Hypercolumn [16]	30.1	81.0	69.3	70.6	60.8	27.3	60.7	45.6	77.3	<b>61.8</b>	58.6
Proposed Method	<b>33.6</b>	<b>82.2</b>	<b>71.2</b>	<b>71.9</b>	<b>63.7</b>	<b>31.1</b>	<b>65.1</b>	<b>49.6</b>	<b>78.9</b>	61.5	<b>60.3</b>
<i>With superpixel projection and rescoring:</i>											
Hypercolumn [16]	30.1	82.0	73.1	73.3	64.6	37.3	68.9	41.4	75.3	67.9	62.4
Proposed Method	<b>31.8</b>	<b>83.6</b>	<b>75.5</b>	<b>74.5</b>	<b>66.6</b>	<b>37.7</b>	<b>70.6</b>	<b>44.7</b>	<b>77.7</b>	<b>68.7</b>	<b>63.6</b>

Table 1: Per-category AP<sup>r</sup> at 50% overlap achieved by the proposed method compared to the state-of-the-art on the PASCAL VOC 2012 validation set.

Setting	aero	bike	bird	boat	bottle	bus	car	cat	chair	cow	
<i>Raw pixel-wise prediction:</i>											
Hypercolumn [16]	52.4	18.6	23.2	15.1	17.3	68.0	36.5	53.5	2.1	26.9	
Proposed Method	<b>61.8</b>	<b>31.5</b>	<b>42.0</b>	<b>22.0</b>	<b>22.7</b>	<b>72.4</b>	<b>44.8</b>	<b>65.4</b>	<b>7.2</b>	<b>37.6</b>	
<i>With superpixel projection:</i>											
Hypercolumn [16]	53.3	26.4	35.4	<b>24.0</b>	22.6	71.0	41.8	61.4	8.4	36.0	
Proposed Method	<b>57.4</b>	<b>33.2</b>	<b>42.9</b>	23.1	<b>23.4</b>	71.0	<b>44.9</b>	<b>64.4</b>	<b>10.8</b>	<b>40.6</b>	
<i>With superpixel projection and rescoring:</i>											
Hypercolumn [16]	55.6	28.7	41.2	<b>26.8</b>	25.5	73.5	45.2	64.7	10.6	42.3	
Proposed Method	<b>61.9</b>	<b>35.1</b>	<b>44.4</b>	26.4	<b>29.6</b>	<b>74.0</b>	<b>48.7</b>	<b>66.8</b>	<b>10.9</b>	<b>48.4</b>	
Setting	table	dog	horse	mbike	person	plant	sheep	sofa	train	tv	mAP <sup>r</sup>
<i>Raw pixel-wise prediction:</i>											
Hypercolumn [16]	8.1	47.4	20.7	35.4	15.6	7.2	28.4	14.9	53.2	44.3	29.4
Proposed Method	<b>10.4</b>	<b>60.4</b>	<b>39.6</b>	<b>41.9</b>	<b>32.5</b>	<b>12.0</b>	<b>40.9</b>	<b>19.9</b>	<b>58.8</b>	<b>50.8</b>	<b>38.7</b>
<i>With superpixel projection:</i>											
Hypercolumn [16]	10.9	58.1	32.8	41.2	27.6	10.2	37.6	25.6	56.4	48.3	36.4
Proposed Method	<b>14.3</b>	<b>62.7</b>	<b>42.1</b>	<b>44.1</b>	<b>36.2</b>	<b>11.6</b>	<b>44.4</b>	<b>27.6</b>	<b>60.1</b>	<b>49.7</b>	<b>40.2</b>
<i>With superpixel projection and rescoring:</i>											
Hypercolumn [16]	12.3	60.8	41.7	42.1	27.3	15.5	45.2	<b>23.9</b>	56.6	47.8	39.4
Proposed Method	<b>13.6</b>	<b>64.0</b>	<b>53.0</b>	<b>46.8</b>	<b>33.0</b>	<b>19.0</b>	<b>51.0</b>	23.7	<b>62.2</b>	<b>53.9</b>	<b>43.3</b>

Table 2: Per-category AP<sup>r</sup> at 70% overlap achieved by the proposed method compared to the state-of-the-art on the PASCAL VOC 2012 validation set.

## 2. Additional Visualizations

The following are predictions of the proposed method and the vanilla hypercolumn net on additional images from various categories.

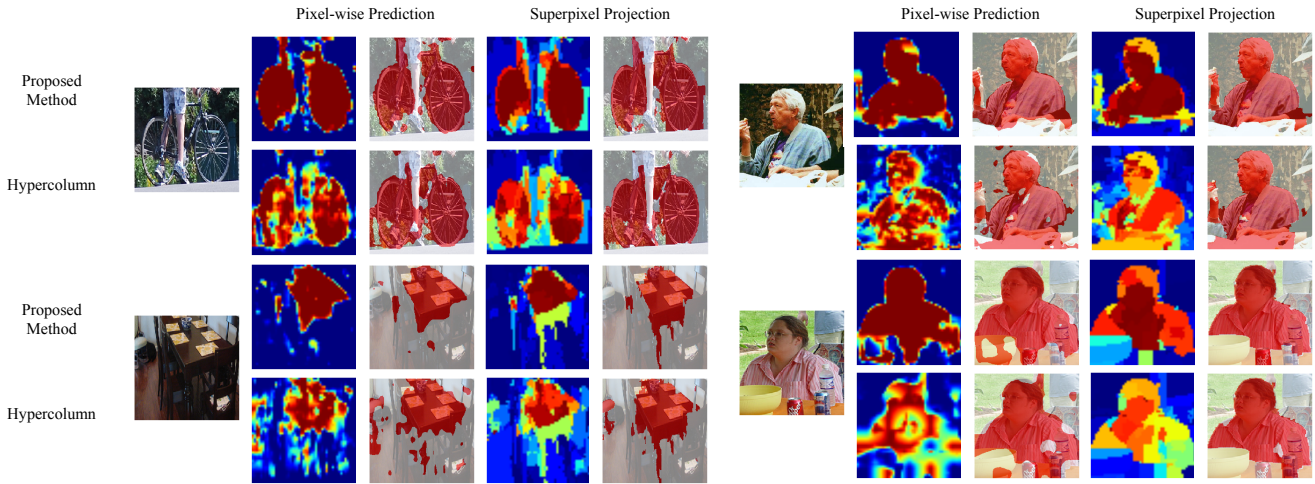


Figure 1: Comparison of heatmap and region predictions produced by the proposed method and the vanilla hypercolumn net on images from the PASCAL VOC 2012 validation set. Best viewed in colour.

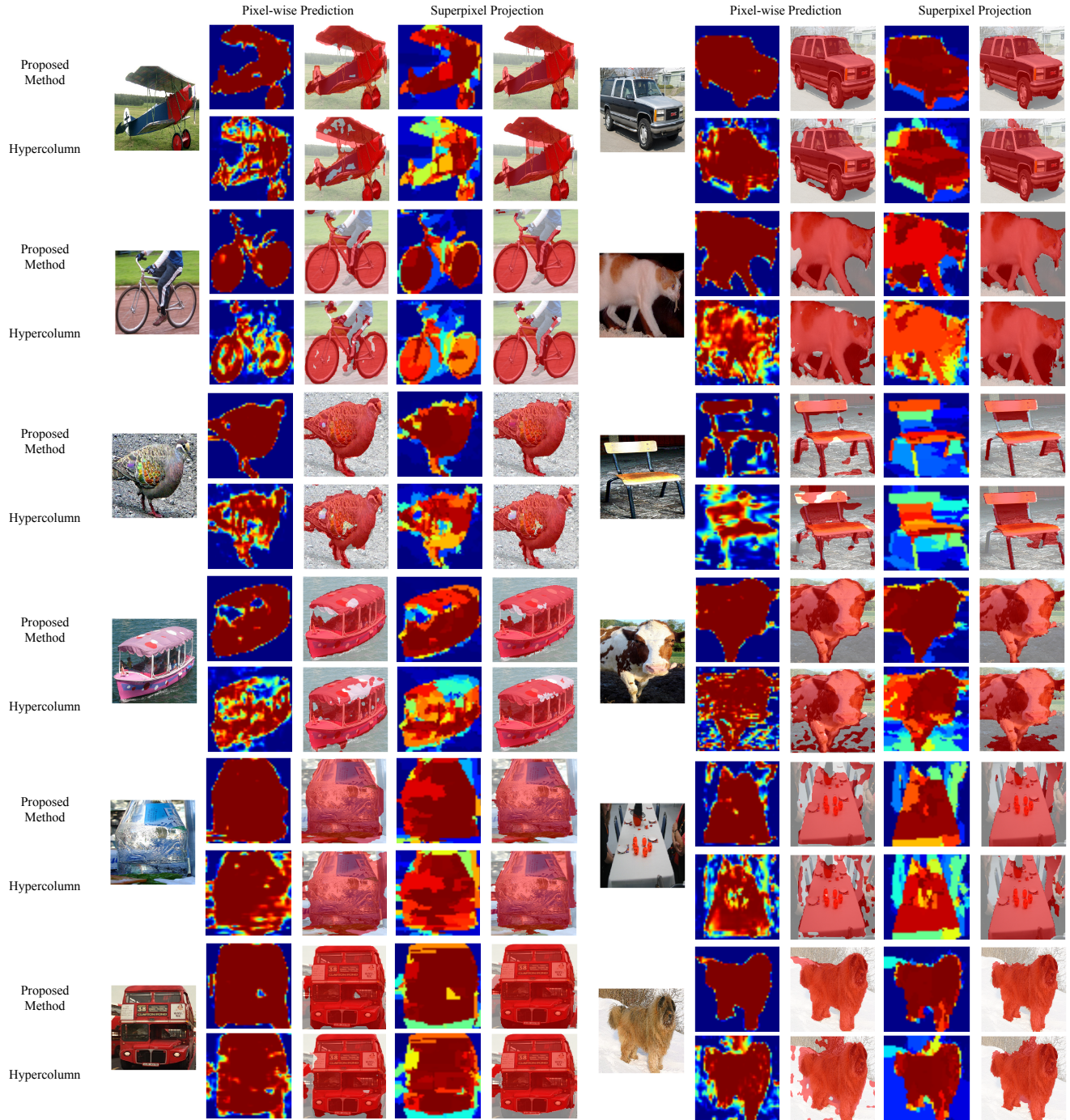


Figure 2: Comparison of heatmap and region predictions produced by the proposed method and the vanilla hypercolumn net on images from the PASCAL VOC 2012 validation set. Best viewed in colour.



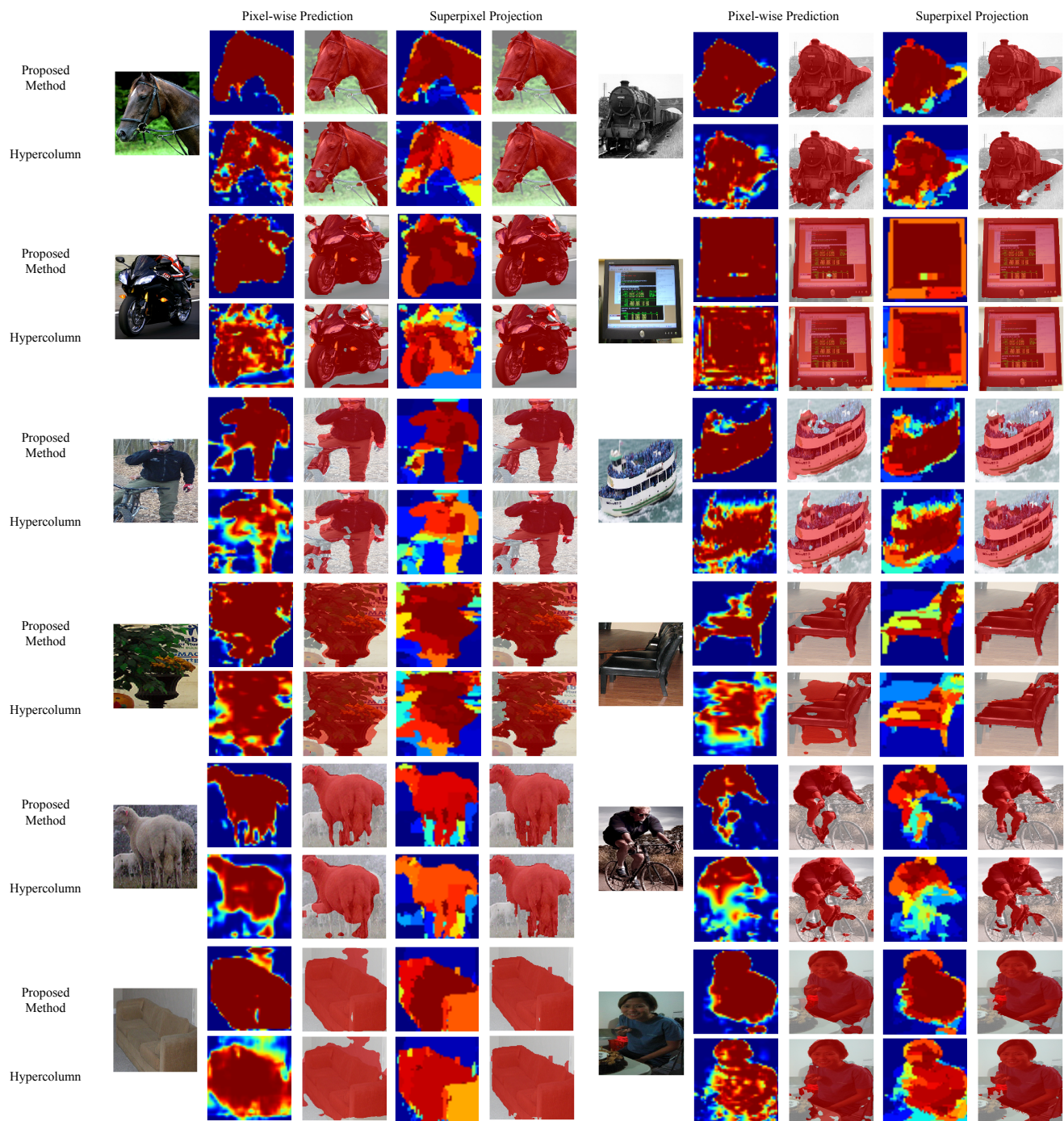


Figure 3: Comparison of heatmap and region predictions produced by the proposed method and the vanilla hypercolumn net on images from the PASCAL VOC 2012 validation set. Best viewed in colour.