



A Matrix Splitting Method for Composite Function Minimization

Ganzhao Yuan^{1,2}, Wei-Shi Zheng², Bernard Ghanem¹

1. King Abdullah University of Science & Technology (KAUST) 2. School of Data & Computer Science, Sun Yat-sen University (SYSU)



1. Composite Function Minimization Problem

$$\min_{\mathbf{x}} f(\mathbf{x}) \triangleq \underbrace{\frac{1}{2}\mathbf{x}^T \mathbf{A} \mathbf{x} + \mathbf{x}^T \mathbf{b}}_{q(\mathbf{x})} + h(\mathbf{x})$$

Assumption: \mathbf{A} is PSD, $h(\cdot)$ is separable

Convex $h(\cdot)$	Nonconvex $h(\cdot)$
$h(\mathbf{x}) = \ \mathbf{x}\ _1$	$h(\mathbf{x}) = \ \mathbf{x}\ _0$
$h(\mathbf{x}) = \begin{cases} 0, & \mathbf{x} \geq 0; \\ \infty, & \text{else.} \end{cases}$	$h(x) = \begin{cases} 0, & \mathbf{x} \in \{0, 1\}^n; \\ \infty, & \text{else.} \end{cases}$

2. Existing Solution: Proximal Gradient Method

$$\mathbf{x}^{k+1} \Leftarrow \min_x g(x, x^k) + h(x)$$

$$\forall \mathbf{z}, \mathbf{x}, q(\mathbf{x}) \leq \underbrace{q(\mathbf{z}) + \langle \nabla q(\mathbf{z}), \mathbf{x} - \mathbf{z} \rangle + \frac{L}{2} \|\mathbf{x} - \mathbf{z}\|_2^2}_{g(\mathbf{x}, \mathbf{z})}$$

$$\mathbf{x}^{k+1} = \text{prox}_{\gamma h}(\mathbf{x}^k - \gamma \nabla q(\mathbf{x}^k))$$

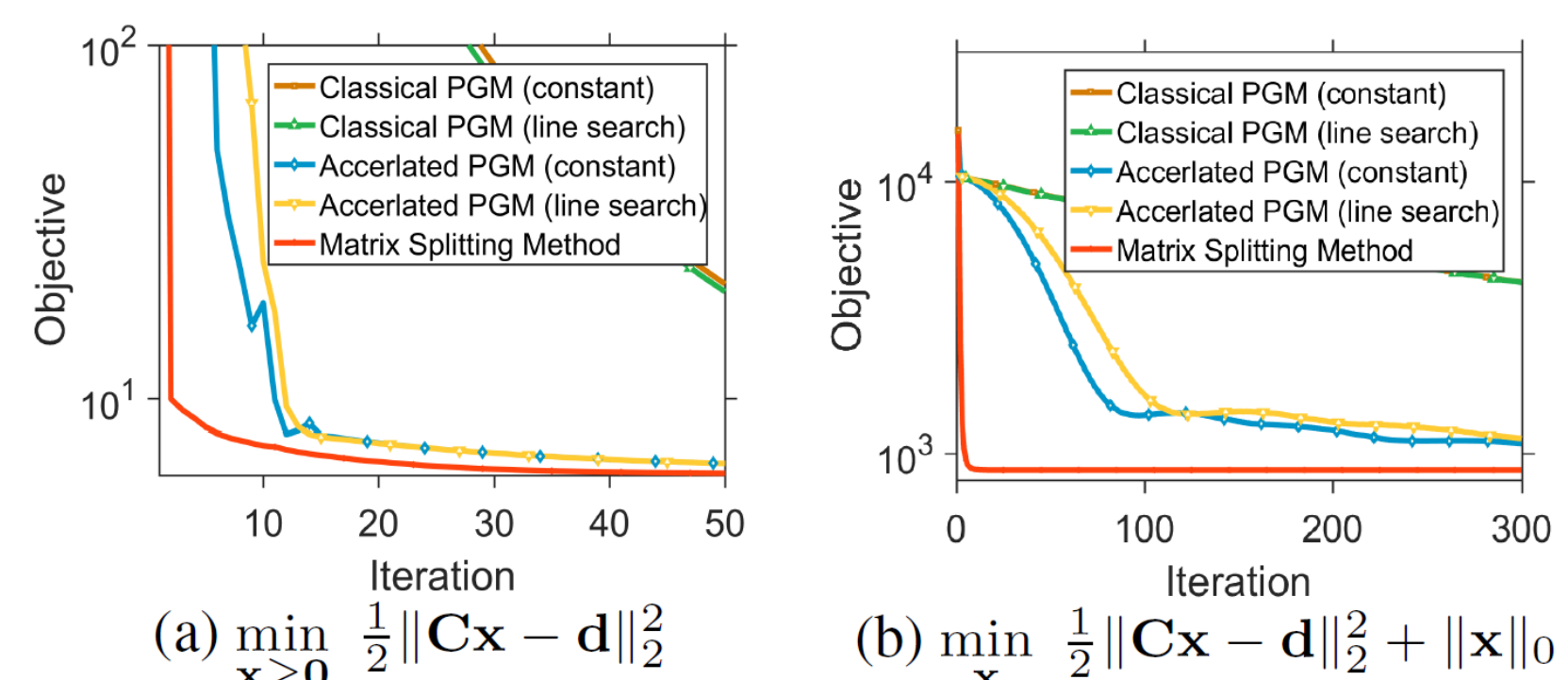
$$\text{prox}_{\tilde{h}}(\mathbf{a}) = \arg \min_{\mathbf{x}} \frac{1}{2} \|\mathbf{x} - \mathbf{a}\|_2^2 + \tilde{h}(\mathbf{x}) = (\mathbf{I} + \partial \tilde{h})^{-1}(\mathbf{a})$$

3. Motivation

$$\text{prox}_{\tilde{h}}(\mathbf{a}) = \arg \min_{\mathbf{x}} \frac{1}{2} \|\mathbf{x} - \mathbf{a}\|_{\mathbf{B}}^2 + \tilde{h}(\mathbf{x})$$

Existing Method	New Method
\mathbf{B} = Scaled Identity Matrix	\mathbf{B} = Triangle Matrix
Closed Form Solution	Closed Form Solution
Proximal Operator	Triangle Proximal Operator
$\text{prox}_{\tilde{h}}(\mathbf{a}) = (\mathbf{I} + \partial \tilde{h})^{-1}(\mathbf{a})$	$\text{prox}_{\tilde{h}}(\mathbf{a}) = (\mathbf{B} + \partial \tilde{h})^{-1}(\mathbf{a})$
↑ resolvent of \tilde{h}	↑ triangle resolvent of \tilde{h} ?

4. A Toy Problem



Our matrix splitting method significantly outperforms existing popular proximal gradient methods in term of both efficiency and efficacy.

5. Proposed Matrix Splitting Method

$$\mathbf{A} \triangleq \mathbf{L} + \mathbf{D} + \mathbf{L}^T$$

$$\triangleq \underbrace{\mathbf{L} + \frac{1}{\omega}(\mathbf{D} + \theta \mathbf{I})}_{\mathbf{B}} + \underbrace{\mathbf{L}^T + \frac{1}{\omega}((\omega - 1)\mathbf{D} - \theta \mathbf{I})}_{\mathbf{C}} \quad \mathbf{D} = \begin{bmatrix} \mathbf{A}_{1,1} & 0 & 0 \\ 0 & \mathbf{A}_{2,2} & 0 \\ 0 & 0 & \mathbf{A}_{3,3} \end{bmatrix}, \mathbf{L} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{2,1} & 0 & 0 \\ \mathbf{A}_{3,1} & \mathbf{A}_{3,2} & 0 \end{bmatrix}$$

➤ Optimality Condition \rightarrow Fixed-Point: $\mathbf{x} = \mathcal{T}(\mathbf{x})$

$$\mathbf{0} \in (\mathbf{B} + \mathbf{C})\mathbf{x} + \mathbf{b} + \partial h(\mathbf{x})$$

$$-\mathbf{C}\mathbf{x} - \mathbf{b} \in (\mathbf{B} + \partial h)\mathbf{x}$$

$$\mathbf{x} \in -(\mathbf{B} + \partial h)^{-1}(\mathbf{C}\mathbf{x} + \mathbf{b})$$

➤ Fixed-Point Iterative Scheme

$$\mathbf{x}^{k+1} = \mathcal{T}(\mathbf{x}^k) \triangleq (\mathbf{B} + \partial h)^{-1}(-\mathbf{C}\mathbf{x}^k - \mathbf{b})$$

➤ How to compute operator $\mathcal{T}(\mathbf{x}^k)$

find \mathbf{z}^* that: $\mathbf{0} \in \mathbf{B}\mathbf{z}^* + \mathbf{u} + \partial h(\mathbf{z}^*)$, where $\mathbf{u} = \mathbf{b} + \mathbf{C}\mathbf{x}^k$

➤ Using forward substitution !

$$\mathbf{0} \in \begin{bmatrix} \mathbf{B}_{1,1} & 0 & 0 & 0 & 0 \\ \mathbf{B}_{2,1} & \mathbf{B}_{2,2} & 0 & 0 & 0 \\ \vdots & \vdots & \ddots & 0 & 0 \\ \mathbf{B}_{n-1,1} & \mathbf{B}_{n-1,2} & \cdots & \mathbf{B}_{n-1,n-1} & 0 \\ \mathbf{B}_{n,1} & \mathbf{B}_{n,2} & \cdots & \mathbf{B}_{n,n-1} & \mathbf{B}_{n,n} \end{bmatrix} \begin{bmatrix} \mathbf{z}_1^* \\ \mathbf{z}_2^* \\ \vdots \\ \mathbf{z}_{n-1}^* \\ \mathbf{z}_n^* \end{bmatrix} + \mathbf{u} + \partial h(\mathbf{z}^*)$$

➤ It reduces to 1-dimensional sub-problem

$$\mathbf{0} \in \mathbf{B}_{j,j}\mathbf{z}_j^* + \mathbf{w}_j + \partial h(\mathbf{z}_j^*), \text{ where } \mathbf{w}_j = \mathbf{u}_j + \sum_{i=1}^{j-1} \mathbf{B}_{j,i}\mathbf{z}_i^*$$

$$\mathbf{z}_j^* = t^* \triangleq \arg \min_t \frac{1}{2} \mathbf{B}_{j,j} t^2 + \mathbf{w}_j t + h(t)$$

6. Convergence Results

➤ Condition $\delta \triangleq \frac{2\theta}{\omega} + \frac{2-\omega}{\omega} \min(\text{diag}(\mathbf{D})) > 0$. Simple Choice $\omega \in (0, 2)$, $\theta = 0.01$

➤ Monotone Non-increasing and Convergent

$$f(\mathbf{x}^{k+1}) - f(\mathbf{x}^k) \leq -\frac{\delta}{2} \|\mathbf{x}^{k+1} - \mathbf{x}^k\|_2^2$$

➤ Q-linear Convergence Rate

$$\frac{f(\mathbf{x}^{k+1}) - f(\mathbf{x}^*)}{f(\mathbf{x}^k) - f(\mathbf{x}^*)} \leq \frac{C_1}{1 + C_1}$$

➤ Iteration Complexity

$$f(\mathbf{x}^k) - f(\mathbf{x}^*) \leq \begin{cases} u^0 (\frac{2C_4}{2C_4+1})^k, & \text{if } \sqrt{f^k - f^{k+1}} \geq C_3/C_4, \forall k \leq \bar{k} \\ \frac{C_5}{k}, & \text{if } \sqrt{f^k - f^{k+1}} < C_3/C_4, \forall k \geq 0 \end{cases}$$

7. Extension to Nonconvex Case

➤ Using the same method to compute $\mathcal{T}(\mathbf{x}^k)$. It reduces to

$$t^* \triangleq \arg \min_t \frac{1}{2} \mathbf{B}_{j,j} t^2 + \mathbf{w}_j t + h(t)$$

➤ Condition $\delta \triangleq \min(\theta/\omega + (1-\omega)/\omega \cdot \text{diag}(\mathbf{D})) > 0$. Simple Choice $\omega < 1$, $\theta = 0.01$

➤ Convergence Result (Monotonically Nonincreasing and Convergent)

$$f(\mathbf{x}^{k+1}) - f(\mathbf{x}^k) \leq -\frac{\delta}{2} \|\mathbf{x}^{k+1} - \mathbf{x}^k\|_2^2$$

8. Extension to Matrix Case

$$\min_{\mathbf{X} \in \mathbb{R}^{n \times r}} f(\mathbf{X}) \triangleq \underbrace{\frac{1}{2} \text{tr}(\mathbf{X}^T \mathbf{A} \mathbf{X}) + \text{tr}(\mathbf{X}^T \mathbf{R})}_{q(\mathbf{X})} + h(\mathbf{X})$$

➤ Applications: NMF, Sparse Coding.

➤ Using the same method to decompose \mathbf{A}

➤ Solve the following nonlinear equation w.r.t. \mathbf{Z}^* : $\mathbf{A} = \mathbf{B} + \mathbf{C}$

➤ It can be decomposed into independent components.

$$\mathbf{B}\mathbf{Z}^* + \mathbf{R} + \mathbf{C}\mathbf{X}^k + \partial h(\mathbf{Z}^*) \in \mathbf{0}$$

9. Extension to Non-Quadratic Case

➤ Majorization Minimization $\mathbf{x}^{k+1} \Leftarrow \min_x g(x, x^k) + h(x)$

➤ Quadratic Surrogate (Second Order Upper Bound)

$$q(x) \leq g(x, x^k) \triangleq q(x^k) + \langle \nabla q(x^k), x - x^k \rangle + \frac{1}{2} (x - x^k)^T M (x - x^k)$$

with $M \succeq \nabla^2 f(x^k)$

➤ Line Search (as in Damped Newton): $\mathbf{x}^{k+1} \Leftarrow \mathbf{x}^k + \beta(\mathbf{x}^{k+1} - \mathbf{x}^k)$

10. Experiments

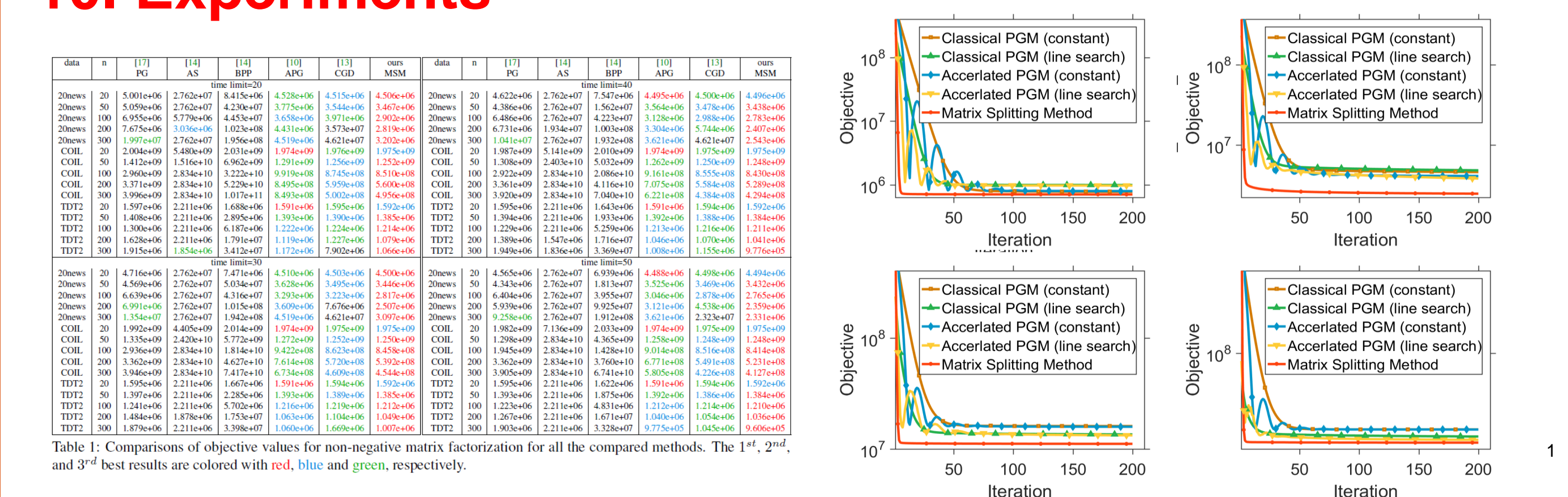


Table 1: Comparisons of objective values for non-negative matrix factorization for all the compared methods. The 1st, 2nd, and 3rd best results are colored with red, blue and green, respectively.

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