



A Matrix Splitting Method for Composite Function Minimization

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1. Composite Function Minimization Problem

$$\min_{\mathbf{x}} f(\mathbf{x}) \triangleq \underbrace{\frac{1}{2} \mathbf{x}^T \mathbf{A} \mathbf{x} + \mathbf{x}^T \mathbf{b}}_{q(\mathbf{x})} + h(\mathbf{x})$$

Assumption: \mathbf{A} is PSD, $h(\cdot)$ is separable

Convex $h(\cdot)$

$$h(\mathbf{x}) = \|\mathbf{x}\|_1$$

$$h(\mathbf{x}) = \begin{cases} 0, & \mathbf{x} \geq \mathbf{0}; \\ \infty, & \text{else.} \end{cases}$$

Nonconvex $h(\cdot)$

$$h(\mathbf{x}) = \|\mathbf{x}\|_0$$

$$h(\mathbf{x}) = \begin{cases} 0, & \mathbf{x} \in \{0, 1\}^n; \\ \infty, & \text{else.} \end{cases}$$

2. Existing Solution: Proximal Gradient Method

$$\mathbf{x}^{k+1} \Leftarrow \min_{\mathbf{x}} g(\mathbf{x}, \mathbf{x}^k) + h(\mathbf{x})$$

$$\forall \mathbf{z}, \mathbf{x}, q(\mathbf{x}) \leq \underbrace{q(\mathbf{z}) + \langle \nabla q(\mathbf{z}), \mathbf{x} - \mathbf{z} \rangle + \frac{L}{2} \|\mathbf{x} - \mathbf{z}\|_2^2}_{g(\mathbf{x}, \mathbf{z})}$$

$$\mathbf{x}^{k+1} = \text{prox}_{\gamma h}(\mathbf{x}^k - \gamma \nabla q(\mathbf{x}^k))$$

$$\text{prox}_{\tilde{h}}(\mathbf{a}) = \arg \min_{\mathbf{x}} \frac{1}{2} \|\mathbf{x} - \mathbf{a}\|_2^2 + \tilde{h}(\mathbf{x}) = (\mathbf{I} + \partial \tilde{h})^{-1}(\mathbf{a})$$

3. Motivation

$$\text{prox}_{\tilde{h}}(\mathbf{a}) = \arg \min_{\mathbf{x}} \frac{1}{2} \|\mathbf{x} - \mathbf{a}\|_{\mathbf{B}}^2 + \tilde{h}(\mathbf{x})$$

Existing Method

\mathbf{B} = Scaled Identity Matrix
Closed Form Solution
Proximal Operator

$$\text{prox}_{\tilde{h}}(\mathbf{a}) = (\mathbf{I} + \partial \tilde{h})^{-1}(\mathbf{a})$$

resolvent of \tilde{h}

New Method

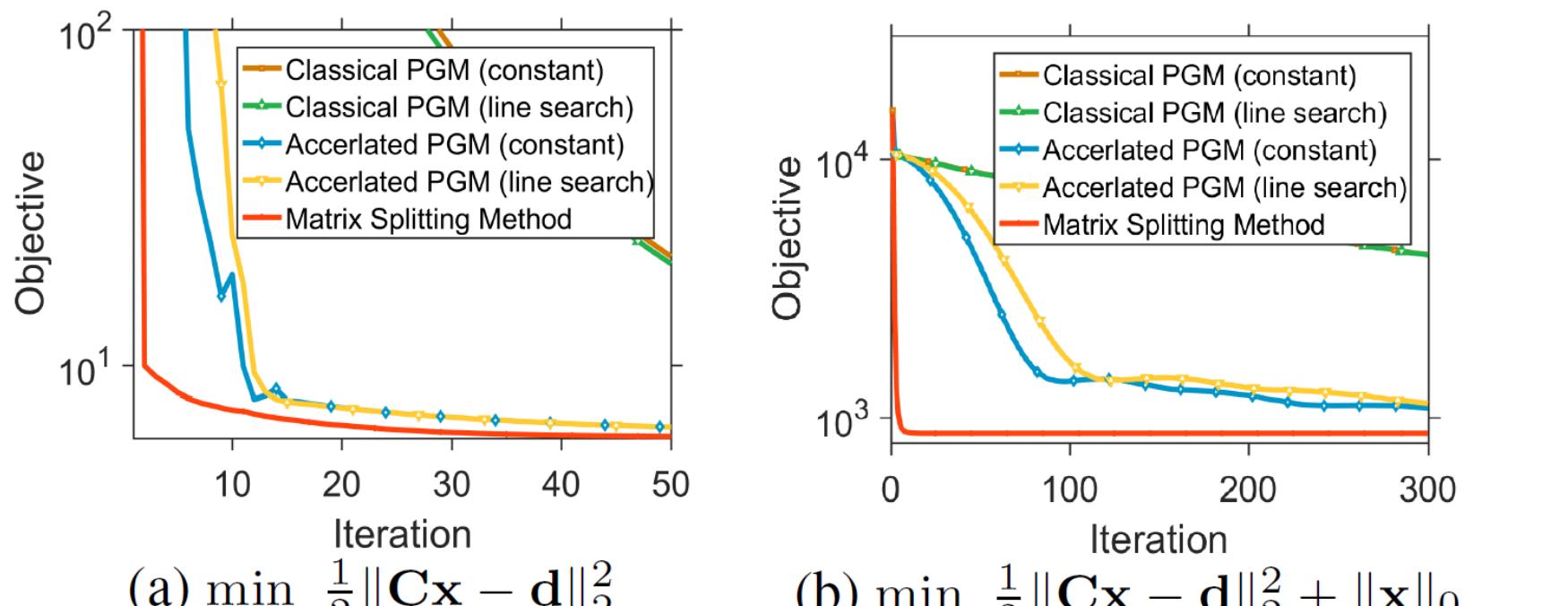
\mathbf{B} = Triangle Matrix
Closed Form Solution

Triangle Proximal Operator

$$\text{prox}_{\tilde{h}}(\mathbf{a}) = (\mathbf{B} + \partial \tilde{h})^{-1}(\mathbf{a})$$

triangle resolvent of \tilde{h} ?

4. A Toy Problem



Our matrix splitting method significantly outperforms existing popular proximal gradient methods in term of both efficiency and efficacy.

5. Proposed Matrix Splitting Method

$$\mathbf{A} \triangleq \mathbf{L} + \mathbf{D} + \mathbf{L}^T$$

$$\triangleq \underbrace{\mathbf{L} + \frac{1}{\omega}(\mathbf{D} + \theta \mathbf{I})}_{\mathbf{B}} + \underbrace{\mathbf{L}^T + \frac{1}{\omega}((\omega - 1)\mathbf{D} - \theta \mathbf{I})}_{\mathbf{C}}$$

$$\mathbf{D} = \begin{bmatrix} \mathbf{A}_{1,1} & 0 & 0 \\ 0 & \mathbf{A}_{2,2} & 0 \\ 0 & 0 & \mathbf{A}_{3,3} \end{bmatrix}, \mathbf{L} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{2,1} & 0 & 0 \\ \mathbf{A}_{3,1} & \mathbf{A}_{3,2} & 0 \end{bmatrix}$$

➤ Optimality Condition → Fixed-Point: $\mathbf{x} = \mathcal{T}(\mathbf{x})$

$$\begin{aligned} \mathbf{0} &\in (\mathbf{B} + \mathbf{C})\mathbf{x} + \mathbf{b} + \partial h(\mathbf{x}) \\ -\mathbf{C}\mathbf{x} - \mathbf{b} &\in (\mathbf{B} + \partial h)\mathbf{x} \\ \mathbf{x} &\in -(\mathbf{B} + \partial h)^{-1}(\mathbf{C}\mathbf{x} + \mathbf{b}) \end{aligned}$$

➤ Fixed-Point Iterative Scheme

$$\mathbf{x}^{k+1} = \mathcal{T}(\mathbf{x}^k) \triangleq (\mathbf{B} + \partial h)^{-1}(-\mathbf{C}\mathbf{x}^k - \mathbf{b})$$

➤ How to compute operator $\mathcal{T}(\mathbf{x}^k)$

find \mathbf{z}^* that: $\mathbf{0} \in \mathbf{B}\mathbf{z}^* + \mathbf{u} + \partial h(\mathbf{z}^*)$, where $\mathbf{u} = \mathbf{b} + \mathbf{C}\mathbf{x}^k$

➤ Using forward substitution !

$$\mathbf{0} \in \begin{bmatrix} \mathbf{B}_{1,1} & 0 & 0 & 0 & 0 \\ \mathbf{B}_{2,1} & \mathbf{B}_{2,2} & 0 & 0 & 0 \\ \vdots & \vdots & \ddots & 0 & 0 \\ \mathbf{B}_{n-1,1} & \mathbf{B}_{n-1,2} & \cdots & \mathbf{B}_{n-1,n-1} & 0 \\ \mathbf{B}_{n,1} & \mathbf{B}_{n,2} & \cdots & \mathbf{B}_{n,n-1} & \mathbf{B}_{n,n} \end{bmatrix} \begin{bmatrix} \mathbf{z}_1^* \\ \mathbf{z}_2^* \\ \vdots \\ \mathbf{z}_{n-1}^* \\ \mathbf{z}_n^* \end{bmatrix} + \mathbf{u} + \partial h(\mathbf{z}^*)$$

➤ It reduces to 1-dimensional sub-problem

$$\begin{aligned} 0 &\in \mathbf{B}_{j,j}\mathbf{z}_j^* + \mathbf{w}_j + \partial h(\mathbf{z}_j^*), \text{ where } \mathbf{w}_j = \mathbf{u}_j + \sum_{i=1}^{j-1} \mathbf{B}_{j,i}\mathbf{z}_i^* \\ \mathbf{z}_j^* &= t^* \triangleq \arg \min_t \frac{1}{2} \mathbf{B}_{j,j}t^2 + \mathbf{w}_j t + h(t) \end{aligned}$$

6. Convergence Results

➤ Condition $\delta \triangleq \frac{2\theta}{\omega} + \frac{2-\omega}{\omega} \min(\text{diag}(\mathbf{D})) > 0$. Simple Choice $\omega \in (0, 2)$, $\theta = 0.01$

➤ Monotone Non-increasing and Convergent

$$f(\mathbf{x}^{k+1}) - f(\mathbf{x}^k) \leq -\frac{\delta}{2} \|\mathbf{x}^{k+1} - \mathbf{x}^k\|_2^2$$

➤ Q-linear Convergence Rate

$$\frac{f(\mathbf{x}^{k+1}) - f(\mathbf{x}^*)}{f(\mathbf{x}^k) - f(\mathbf{x}^*)} \leq \frac{C_1}{1+C_1}$$

➤ Iteration Complexity

$$f(\mathbf{x}^k) - f(\mathbf{x}^*) \leq \begin{cases} u^0 \left(\frac{2C_4}{2C_4+1} \right)^k, & \text{if } \sqrt{f^k - f^{k+1}} \geq C_3/C_4, \forall k \leq \bar{k} \\ \frac{C_5}{k}, & \text{if } \sqrt{f^k - f^{k+1}} < C_3/C_4, \forall k \geq 0 \end{cases}$$

7. Extension to Nonconvex Case

➤ Using the same method to compute $\mathcal{T}(\mathbf{x}^k)$. It reduces to

$$t^* \triangleq \arg \min_t \frac{1}{2} \mathbf{B}_{j,j}t^2 + \mathbf{w}_j t + h(t)$$

➤ Condition $\delta \triangleq \min(\theta/\omega + (1-\omega)/\omega \cdot \text{diag}(\mathbf{D})) > 0$. Simple Choice $\omega < 1$, $\theta = 0.01$

➤ Convergence Result (Monotonically Nonincreasing and Convergent)

$$f(\mathbf{x}^{k+1}) - f(\mathbf{x}^k) \leq -\frac{\delta}{2} \|\mathbf{x}^{k+1} - \mathbf{x}^k\|_2^2$$

8. Extension to Matrix Case

$$\min_{\mathbf{X} \in \mathbb{R}^{n \times r}} f(\mathbf{X}) \triangleq \underbrace{\frac{1}{2} \text{tr}(\mathbf{X}^T \mathbf{A} \mathbf{X}) + \text{tr}(\mathbf{X}^T \mathbf{R})}_{q(\mathbf{X})} + h(\mathbf{X})$$

➤ Applications: NMF, Sparse Coding.

➤ Using the same method to decompose \mathbf{A}

➤ Solve the following nonlinear equation w.r.t. \mathbf{Z}^* : $\mathbf{A} = \mathbf{B} + \mathbf{C}$

➤ It can be decomposed into independent components.

$$\mathbf{B}\mathbf{Z}^* + \mathbf{R} + \mathbf{C}\mathbf{X}^k + \partial h(\mathbf{Z}^*) \in \mathbf{0}$$

9. Extension to Non-Quadratic Case

➤ Majorization Minimization $\mathbf{x}^{k+1} \Leftarrow \min_{\mathbf{x}} g(\mathbf{x}, \mathbf{x}^k) + h(\mathbf{x})$

➤ Quadratic Surrogate (Second Order Upper Bound)

$$q(\mathbf{x}) \leq g(\mathbf{x}, \mathbf{x}^k) \triangleq q(\mathbf{x}^k) + \langle \nabla q(\mathbf{x}^k), \mathbf{x} - \mathbf{x}^k \rangle + \frac{1}{2} (\mathbf{x} - \mathbf{x}^k)^T M (\mathbf{x} - \mathbf{x}^k)$$

with $M \succeq \nabla^2 f(\mathbf{x}^k)$

➤ Line Search (as in Damped Newton): $\mathbf{x}^{k+1} \Leftarrow \mathbf{x}^k + \beta(\mathbf{x}^{k+1} - \mathbf{x}^k)$

10. Experiments

data	n	[1][2]	[3][4]	[5][6]	[7][8]	[9][10]	[11][12]	[13][14]	[15][16]	[17][18]	[19][20]	[21][22]	[23][24]	[25][26]	[27][28]	[29][30]	[31][32]	[33][34]	[35][36]	[37][38]	[39][40]	[41][42]	[43][44]	[45][46]	[47][48]	[49][50]	[51][52]	[53][54]	[55][56]
Sh01	20	5.00e+00	2.76e+00	1.62e+00	1.00e+00	4.54e+00	2.40e+00	1.25e+00	6.25e+00	3.12e+00	1.56e+00	7.76e+00	4.00e+00	1.96e+00	9.80e+00	4.90e+00	2.45e+00	1.22e+00	6.10e+00	3.05e+00	1.52e+00	7.60e+00	3.80e+00	1.90e+00	9.50e+00	4.75e+00	2.37e+00	1.18e+00	
Sh02	20	5.00e+00	2.76e+00	1.62e+00	1.00e+00	4.54e+00	2.40e+00	1.25e+00	6.25e+00	3.12e+00	1.56e+00	7.76e+00	4.00e+00	1.96e+00	9.80e+00	4.90e+00	2.45e+00	1.22e+00	6.10e+00	3.05e+00	1.52e+00	7.60e+00	3.80e+00	1.90e+00	9.50e+00	4.75e+00	2.37e+00	1.18e+00	
Sh03	100	6.00e+00	3.77e+00	2.43e+00	1.40e+00	5.77e+00	3.43e+00	1.80e+00	9.00e+00	4.50e+00	2.25e+00	1.12e+00	5.60e+00	3.00e+00	1.50e+00	7.50e+00	4.00e+00	2.00e+00	1.00e+00	5.00e+00	2.50e+00	1.25e+00	6.25e+00	3.12e+00	1.56e+00	7.80e+00	4.00e+00	2.00e+00	1.00e+00
Sh04	100	6.00e+00	3.77e+00	2.43e+00	1.40e+00	5.77e+00																							